### Exploiting Lag-Time Information for Optimizing Network Inference

Nicolas Rubido<sup>1</sup> and <u>Cristina Masoller<sup>2</sup></u>

<sup>1</sup>Universidad de la República, Montevideo, Uruguay <sup>2</sup>Universitat Politecnica de Catalunya, Terrassa, Barcelona, Spain

cristina.masoller@upc.edu

www.fisica.edu.uy/~cris

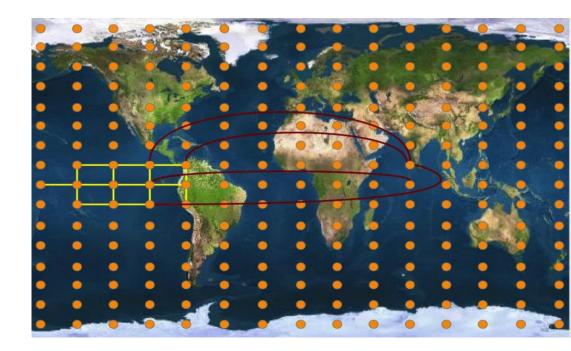


NOLTA 2018, Tarragona, Spain

Campus d'Excel·lència Internacional

### Motivation: how to infer the connectivity of a complex system from observed data?





Spatial grid points used for building climate networks

### Linear and nonlinear correlation analysis are used for inferring undirected links

Time series recorded at nodes i an j:  $a_i(t)$ ,  $a_i(t)$ , t=1, ..., T

- Lagged cross correlation  $CC_{ij}(\tau_{ij}) = \frac{1}{T \tau_{max}} \left| \sum_{t=0}^{T \tau_{max}} a_i(t) a_j(t + \tau_{ij}) \right|$
- Mutual information
  - Histograms

$$MI_{ij}(\tau_{ij}) = \sum_{m,n} p_{ij}(m, n) \log_2 \left( \frac{p_{ij}(m, n)}{p_i(m) p_j(n)} \right)$$

Symbolic (ordinal) patterns

 $p_i$  is the prob. that  $a_i(t)$  lies in bin i  $p_j$  is the prob. that  $a_i(t+\tau_{ij})$  lies in bin j

Statistical Similarity Measure (SSM): CC or MI

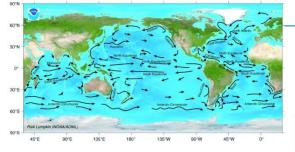
$$SSM_{ij} = maxSSM_{ij}(\tau_{ij}) \quad \tau_{max} =$$

 $\tau_{max} = T/5$ 

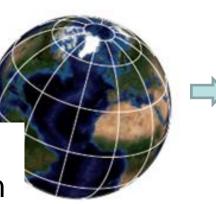
If **SSM** ii > **TH** the link i  $\leftarrow \rightarrow$  j exists, otherwise, it does not exist.

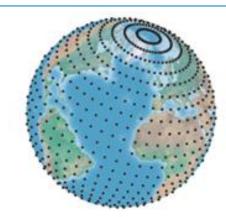


## Complex network representation of the climate system



#### Back to the climate system: interpretation (currents, winds, etc.)





More than 10000 nodes.



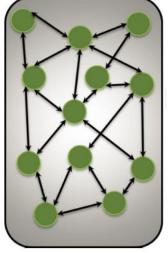
Daily resolution: more than 13000 data points in each TS

Surface Air Temperature <u>Anomalies</u> (solar cycle removed)

Donges et al, Chaos 2015

### Can we test which Statistical Similarity Measure is optimal for inferring the network connectivity?

- 12 chaotic Rossler oscillators with known random connectivity (19 undirected links).
- The x variable is recorded for different coupling strengths (K)



12 Measured Signals for each K

 From the observed signals, different time series can be derived.

# $\{ x_i \} \Longrightarrow \{ \phi_i \} = HT[x_i] \Longrightarrow \{ f_i \} = d\phi_i / dt$ Hilbert transform

Which one is the "best"?

How to quantify the success of network inference?

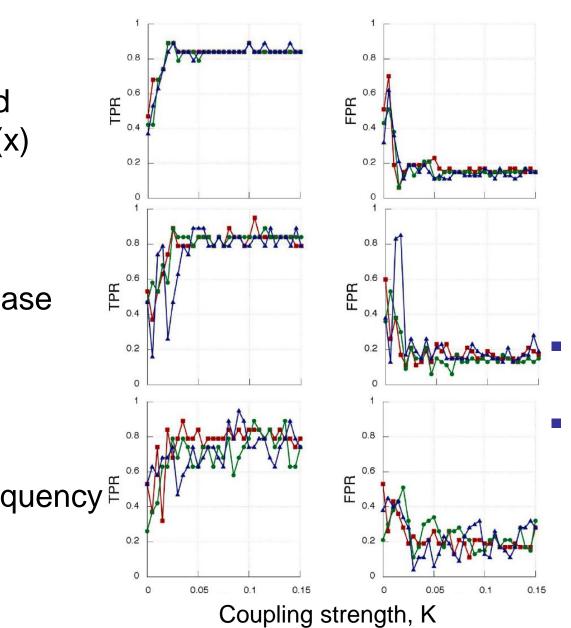
- True positive rate: number of correctly detected links / number of existing links;
- False negative rate: number of links which are incorrectly classified as not existing / number of existing links;
- True negative rate: number of correctly identified nonexisting links / number of non-existing links;
- False positive rate: number of non-existing links which are incorrectly classified as existing / number of non-existing links.

#### Results

Observed variable (x)

Hilbert phase

0.6 Hilbert frequency



Detection threshold **TH** chosen to minimize errors. Statistical similarity measures:

CC MI **MI(symbols)** 

No perfect reconstruction

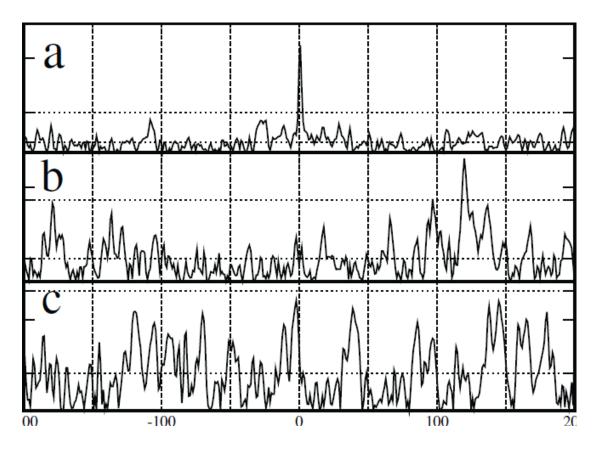
No difference between the SSMs & variables

G. Tirabassi et al, Sci. Rep. **5** 10829 (2015)

#### Can we use the lag information to improve the inference?

$$SSM_{ij} = \max_{\tau_{ij}} SSM_{ij}(\tau_{ij})$$

An example from observed climatic data (temperature anomalies)



A strongly correlated link, with small time delay

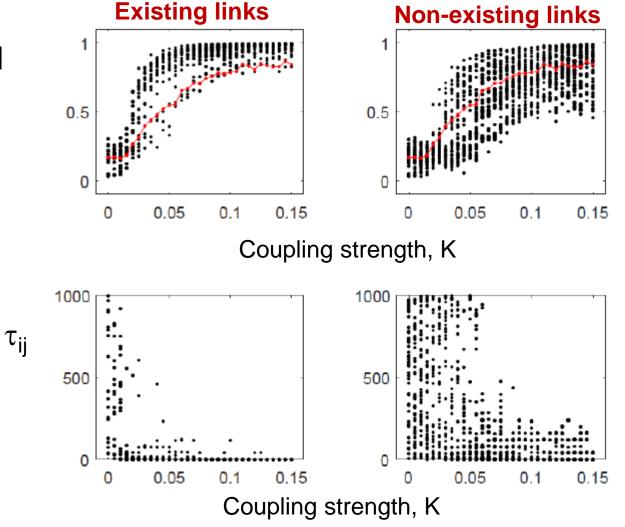
An intermediately correlated link, with a few significant time delays.

A weakly correlated link, where the local maxima cannot be distinguished from noise.

Gozolchiani et al, EPL, 83 (2008) 28005

#### Lag analysis of the chaotic Rossler oscillators

Statistical similarity measure (CC)



### We use two thresholds and compare three criteria to infer the network

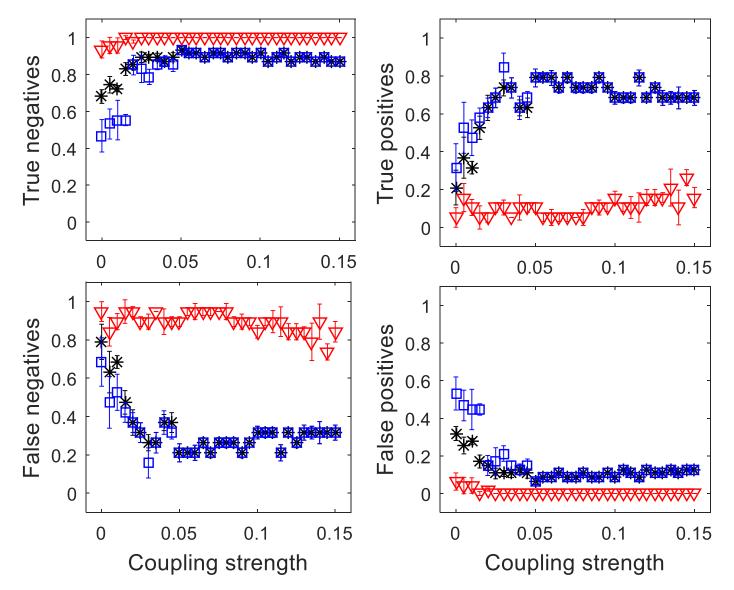
**SIM**: Only the similarity measure (CC) is used to infer the links. The link between *i* and *j* exists  $(A_{ij}^* = 1)$  if  $S_{ij} > S_{th}$ , else, the link does not exist  $(A_{ij}^* = 0)$ .

**AND**: The link between *i* and *j* exists  $(A_{ij}^* = 1)$  if  $\tau_{ij} < \tau_{th}$  and  $S_{ij} > S_{th}$ , else, the link does not exist  $(A_{ij}^* = 0)$ .

**OR**: The link between *i* and *j* exists  $(A_{ij}^* = 1)$  if  $\tau_{ij} < \tau_{th}$  or  $S_{ij} > S_{th}$ , else, the link does not exist  $(A_{ij}^* = 0)$ .

The detection thresholds  $S_{th}$  and  $\tau_{th}$  are chosen to return a given number of links (we assume that we know the number of nodes and the number of links).

#### **Results**

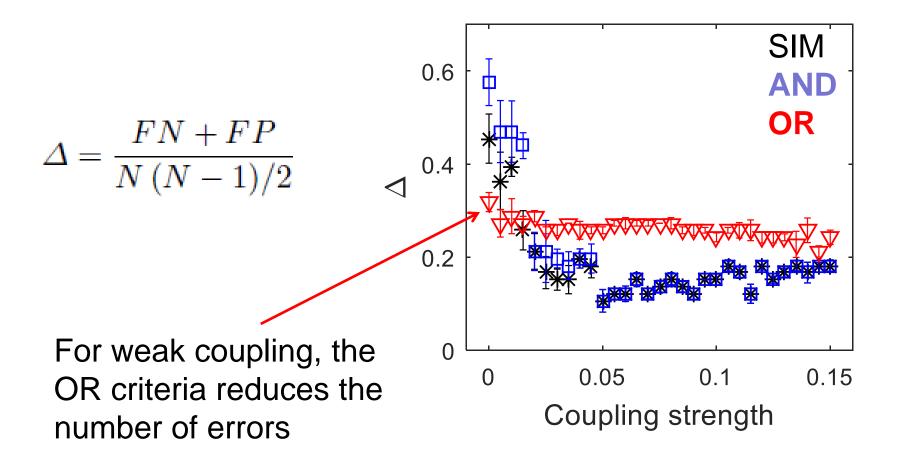


#### SIM AND OR

For large coupling SIM & AND give similar results.

OR minimizes the false positives but fails to detect existing links.

#### Total errors (% of wrongly inferred links)



#### What did we learn?

- For strong coupling, lag information can be used to minimize the false positives but is detrimental to detect existing links.
- For weak coupling, lag information reduces the total number of mistakes.
- **Future work**: are these results robust to other types of oscillatory coupled systems?

#### Thank you for your attention

http://www.fisica.edu.uy/~cris

G. Tirabassi et al, Sci. Rep. 5 10829 (2015) N. Rubido and C. Masoller, arXiv:1807.09636 (2018)

