Reconstructing the State Space of Dynamical Systems from Data: Comparison Between 1D Spatially Extended and Time Delayed Systems

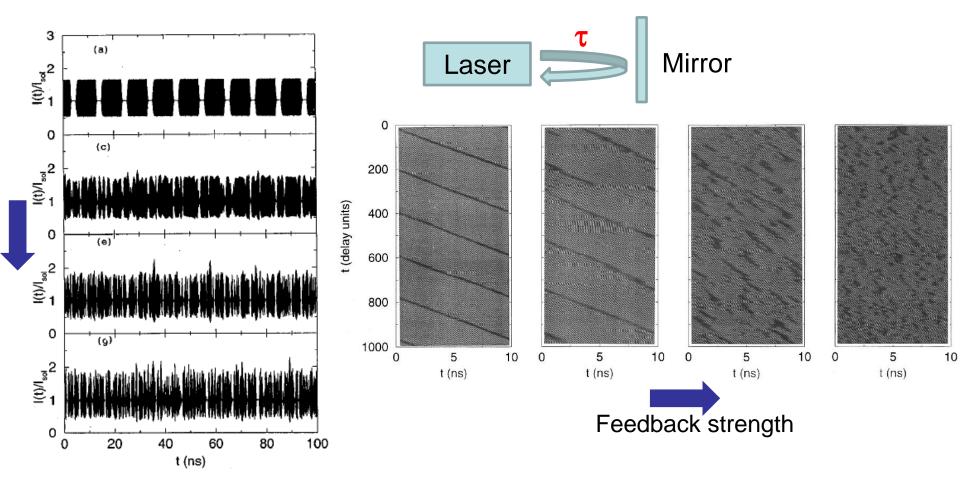
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In a diode laser, time-delay feedback induces chaos

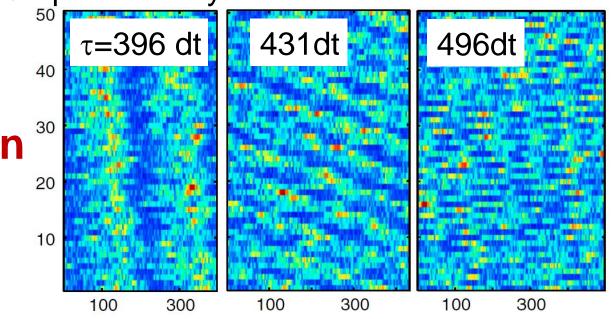


Similar to pattern formation in spatio-temporal systems

- F. T. Arecchi et al, Phys. Rev. A 45, R4225 (1992).
- C. Masoller, "Spatiotemporal dynamics of semiconductor lasers with feedback", Chaos 7, 455 (1997).

The space-time representation: a convenient way to uncover underlying structure in data

Output intensity of a fiber laser



Aragoneses et al, PRL (2016)

Space-time analogy

- Space-time dynamical systems and time-delayed systems both live in an infinite phase space: an initial function –in space or in time– needs to be specified in order to obtain the system's evolution.
- Do they have similar "attractors"?
- We analyze bi-stable systems, described by a state variable u:
 - Space time system: u(space, time)
 - Time delay system: u(time).

1D Spatially extended system

1D Time delayed system

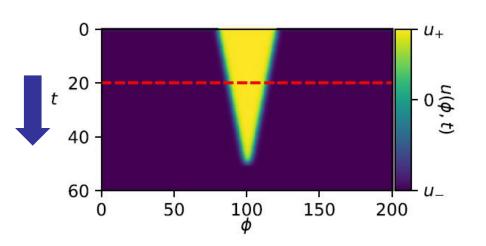
 $du/dt = F(u) + \gamma u_{\tau}$ $u_{\tau} = u(t - \tau)$

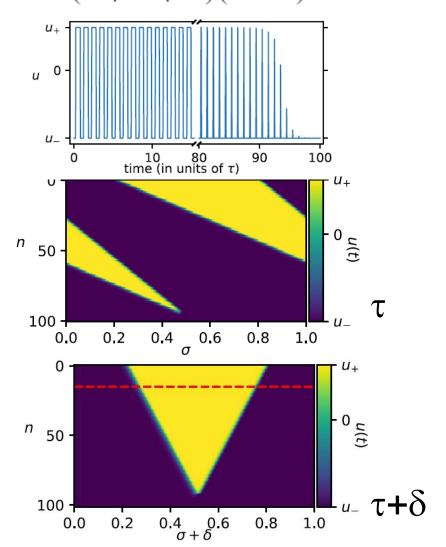
ø space
variable

$$\partial_t u = F(u) + D\partial_\phi^2 u$$

$$F(u) = -dV(u)/du = -u(u + 1 + \alpha)(u - 1)$$

bistable function





Reconstruction of the attractors

Spatially extended system

$$\partial_t u = F(u) + D\partial_{\phi}^2 u$$

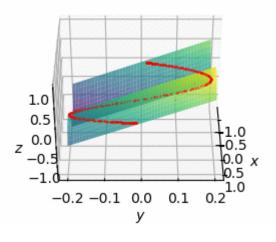
$$x = u, \quad y = \partial_{\phi}^2 u, \quad z = \partial_t u$$

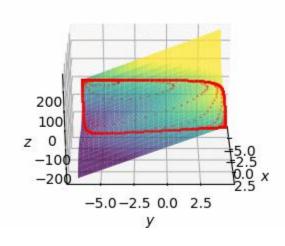
Time delayed system

$$du/dt = F(u) + \gamma u_{\tau}$$

$$x = u, \quad y = u_{\tau}, \quad z = du/dt$$

$$z = \mathcal{F}(x, y) = F(x) + Dy$$
 2D manifold
Bünner et al. PRL 1996





C. Quintero-Quiroz, M. C. Torrent and C. Masoller, "State space reconstruction of spatially extended systems and of time delayed systems from the time series of a scalar variable", Chaos 28, 075504 (2018).

Test: model of delay-coupled lasers

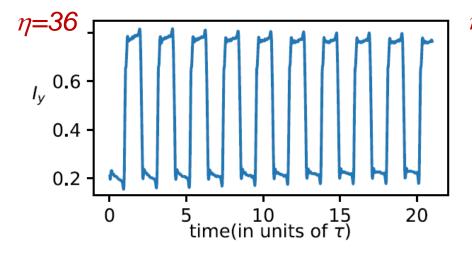
$$\frac{dE_{x,i}}{dt} = k(1+j\psi)(g_{x,i}-1)E_{x,i} + \sqrt{\beta_{sp}}\xi_{x,i},$$

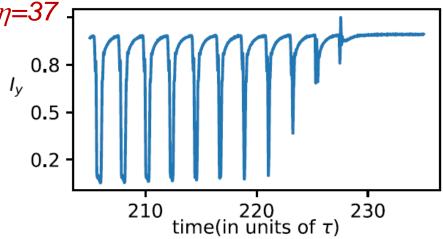
$$\frac{dE_{y,i}}{dt} = j\Delta E_{y,i} + k(i+j\alpha_l)(g_{y,i}-1-\beta)E_{y,i}$$

$$+ \eta E_{x,3-i}(t-\tau)e^{-j\omega_0\tau} + \sqrt{\beta_{sp}}\xi_{y,i},$$

$$dN_i$$

$$\frac{dN_i}{dt} = \varepsilon_N(\mu - N_i - g_{x,i}I_{x,i} - g_{y,i}I_{y,i}),$$





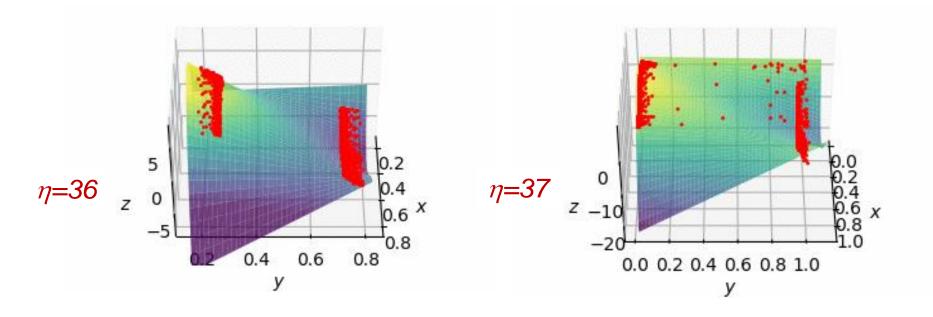
Attractor reconstruction

$$z = \mathcal{F}(x, y) = F(x) + \gamma y$$

Try a polynomial function

$$\mathcal{F}(x,y) = A_0 + A_1 x + A_2 x^2 + A_3 x^3 + A_4 y + A_5 x y + A_6 x^2 y$$

Can we fit numerically the unknown parameters?



C. Quintero-Quiroz, M. C. Torrent and C. Masoller, "State space reconstruction of spatially extended systems and of time delayed systems from the time series of a scalar variable", Chaos 28, 075504 (2018).

Space-time analogy

Can we fit the time-delay system as a spatially extended system using the space-time representation?

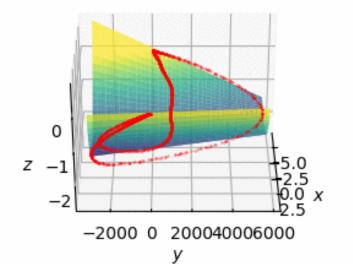
$$\{I_1, I_2, \dots I_{\tau}, I_{\tau+1}, \dots\}$$

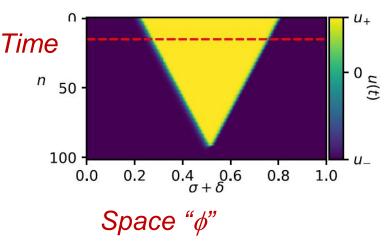
Time delay system

$$x = u$$
, $y = u_{\tau}$, $z = du/dt$

Spatially extended system

$$x = u$$
, $v = \partial_{+}^{2}u$, $z = \partial_{t}u$





These partial derivatives have to be estimated numerically

⇒ Yes, we can obtain a good fit

However, the relation between the fitted parameters and the model parameters is unclear and needs to be further investigated.

Summary

- The evolution of a bi-stable time-delay system and a bi-stable spatially-extended system can be described, in a 3D phase space (x,y,z), by the same polynomial potential.
- More complicated bistable time-delay systems can be described, approximately, in the same way.

Future work: can the 3D representation be useful to investigate regime transitions, coupling and causal relations?

Thank you for your attention

http://www.fisica.edu.uy/~cris

C. Quintero-Quiroz et al., Chaos 28, 075504 (2018) arXiv: 1801.08340





